# HD-400 EXCEED

**Bucket capacity** 

• CECE heaped : 0.22m<sup>3</sup>~0.50m<sup>3</sup> • PCSA, SAE heaped : 0.33 yd<sup>3</sup>~0.75 yd<sup>3</sup>

Engine output : 83 PS/2,100 rpm (JIS, DIN)

82 HP (61kW)/2,100 rpm (SAE, Net)

Gross weight : 10,500kg (23,100lbs)

VII series



The widely acclaimed advanced excavator with





## extensive improvements to satisfy your expectation



# Comfortable king size cab brighten up operating





Crossbar eliminated for wide forward visibility



• Flat floor making access and cleaning easy





One key system



 Safety monitor ensures safety





### environment





•King-size cab meets ISO international standard (940 mm)



Long lever available



 Sturdy frame-structure prevents the engine cover from thedamage



Large tool box





### State-of-the-art technology feel the all advantages

### New "APC" computer system enables use of full engine power

■ An advanced new computer system developed by Kato, New "APC", controls pump output in line with work conditions and site demands. Engine and pump output are matched at optimum levels in a ground-breaking system that exploits 100% of engine power.

### Economical "Auto Slow" system saves fuel consumption while waiting to dump

■ A few seconds after the lever is put into neutral, the fuel-saving "Auto Slow" system automatically drops the engine speed down to an idle. This reduces power loss while waiting to dump, thus cutting fuel waste and further improving overall economy. Noise is reduced, too. Auto Slow has three modes: On, Off and Econo mode

 On mode: Engine speed is automatically reduced; most effective when waiting to dump, etc,

 Off mode: Use the quick accelerator switch to drop speed to idle and then to restore its previous speed.

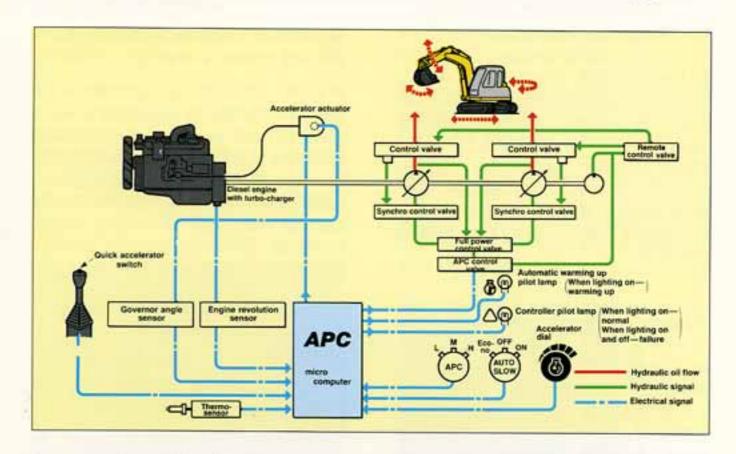
 Econo mode: Engine speed is set at the most efficient production/fuel

consumption. The quick accelerator switch slows down to idle and restores the Econo speed as in Off mode.



#### Six modes let you balance work load with fuel consumption and noise level

■ Changing the "APC" mode (H mode, M mode, L mode) lets the operator automatically control the load ratio on the engine. Econo mode additionally allows the engine speed to be reduced, further lowering fuel consumption and noise by another large step.



### Choose from big-job, fuel-efficiency and small-job modes

■ Choose from any one of three modes of "APC" control depending on the requirements of the job. Select the H mode (which makes maximum use of engine power), the M mode (which changes engine power without reducing engine rpm) or the L mode.

H mode (for greatest productivity): Ideal for jobs that involve lots of digging and earthmoving—enables you to get the work done faster for maximum productivity.

M mode (saves fuel): Greatly reduces fuel while keeping high productivity.

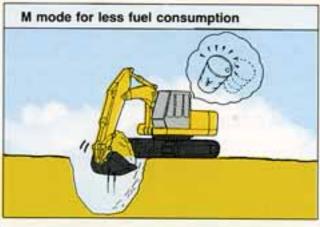
L mode (for precise operation): Optimum for precise jobs like grading, leveling and lifting at minimum fuel consumption.

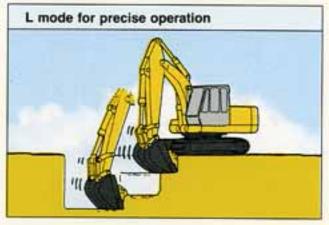
H mode for greatest productivity
 M mode for less fuel consumption
 L mode for precise

operation













### Two-speed travel motor and travel boost system push this machine to the head of its class (5.5kmh/3.4mph)

■ Two-speed travel motor and travel boost system give this machine the highest speed and traction force in its class. Operator can easily select the right travel speed to suit the requirements of the job.

· High speed traveling ......long distance traveling .....traveling on

site, climbing up steep slope or getting out of marshy land

### Wide operating range

■ Digs deeper, higher and wider than any machine in its class. This machine has a maximum digging depth of 5.07m (16'07"), a maximum digging radius of 7.71m (25'03"), a maximum vertical digging depth of 4.52m (14'10"), and a maximum digging height of 8.08m (26'06").

### Greatest digging force

■ Digging force is tops in its class: bucket digging force is 7.3t (16,000lbf) and arm digging force 5.0t (11,000lbf). This exceptional force makes the machine fast and effective even on tough digging jobs like clay and hard dirt.

# Smallest swing radius in machines of its kind—perfect for narrow road jobs

■ The minimum front swing radius is a 2.32m (7'07") only. Combined with the rear swing radius of 2.12m (6'11"), it gives the smallest swing radius of any machine of its size. Urban jobs like water and sewer line construction in tight spaces like tunnels or in crowded residential areas are a snap.



#### Smooth fine control

■ Cushioning mechanism absorbs shocks in the arm cylinder and boom cylinder. The proved swing mechanism ensures the smooth swing without jerks.

### Synchro control system reduces energy waste

■ When the operating lever is in neutral, the pump flow rate is automatically set to a minimum to save fuel and the supply rate is matched to lever stroke. So loss through restriction and discharge from the control valve during inching operations or when in neutral position have been reduced.

### Straight travel system while compound operation

The machine can travel straight even while the compound operation of boom, arm, bucket and swing.

#### High-power, low-fuel-consumption and low-noise direct-injection turbocharged engine

■ Tenacious and reliable, the direct-injection turbo-charged engine is just the start of a thoughtful noise-reducing, fuel-efficient and high-power design. Combined with the New "APC", it creates the great productivity and low fuel costs.



### Innovative "Accel Dial" for engine speed control

■ Engine speed is controlled by finger-touch "Accel Dial" thanks to an electric servomotor. Combination with "Auto Slow" makes the engine control more advanced.

### Light-touch lever-control

■ Light touch servo control levers are employed for ease of operation. Both a wrist control lever and a long lever are available.

### Roomy wide cab for enhanced operator's comfort

- A roomy wide cab features an ISO standard width of 940mm (3'1"). The tinted safety glass, all controls and instruments are ergonomically designed for optimum comfort. The fully reclining bucket type seat with forward/backward, vertical and recline angle adjustment is designed so that the operator will experience a minimum of fatigue, even when working long hours.
- The cab structure is rubbermounted on six positions. The compressed sound-proofing materials are also installed in the cab to isolate engine and other outside noise and vibration from the cab for the operator's comfort.

### Low noise design

■ A number of features have been incorporated to reduce noise, among them the quiet turbo-charged engine, a muffled engine room with a bottom cover, and plenty of sound-absorbing material applied to the engine cover for the low noise inside the cab and in the environment.

### Check machine condition at a glance

■ A safety monitor is provided for inspection prior to commencing

work so that the operator can check the condition of the machine at a glance from the comfort of his seat. In the event of a fault, a red lamp lights and a buzzer sounds to warn the operator.





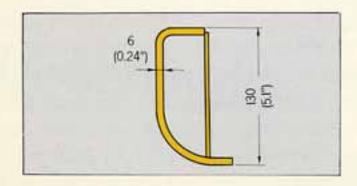
### New design makes maintenance simple

- Tool box is large enough to accommodate tools, a grease can and etc, and the large fuel tank cuts down frequency of refuelling.
- The superstructure is provided with hand-rails and non-slip tapes for safety and easy access during inspections and maintenance.
- Just one key to start the engine as well as locking the cab, machine room and all other locations.
- Radiator net prevents from clogging and easy to slide upwards for easy maintenance.



### Sturdy frame-structure prevents the engine cover from the damage

■ The skirt of the superstructure is so designed, in the rounded, sturdy frame-structure, as to protect the engine cover from accidental contact and shocks.



#### Superstructure-undercover eases travel and work in rough terrain

■ The superstructure is provided with the undercover for easy travel and work in rough terrain.

### Handy centralized lubrication system

- A remote lubrication system makes greasing of high area safe and easy.
- Dust seals and o-rings provided for the front attachment and bucket extend pin life and improve durability.



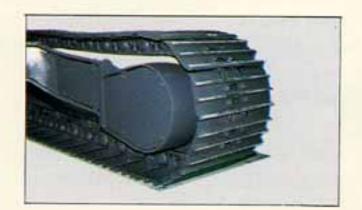
### Bucket clearance is easy to adjust

■ To adjust bucket clatter simply loosen the fitting bolts, remove the flange, add shims to the loose area and then re-tighten to eliminate the clatter.



### Sturdy, stable undercarriage

■ The travel motor is neatly housed inside the track frame with a cover. Sufficient ground clearance assisted by a traveling pipings cover and mud clogging prevention hole located underneath the carrier roller, ensures powerful travel without any fear of the damage even on ungraded land.



#### Swing motor with parking brake ensures safety

Swing mechanical parking brake which prevents free swinging when traveling and on inclines.

#### Safety lock lever

■ Safety lock lever prevents accidental misoperation when getting in and out of the cab.



## **Technical Specifications**



### **ENGINE**

Model	Mitsubishi 4D31T, 4 cycle turbo charged diesel engine
Number of cylinders	4
	100mm (3.9")×105mm (4.1")
	3,298cc (200 in <sup>3</sup> )
nated output	(JIS, D1005-1986, DIN 6270B)
OOLID (C	
a para a constitue de la const	1kW)/2,100rpm (SAE J1349, Net)
Max. torque	30kgf·m/1,700rpm
representational as the transfer	220lbf-ft/1,700rpm
Compression ratio	16.0 : 1
Combustion system	Direct injection
	tion164g/PS-hour
	0.37lb/HP-hour, 222g/kW-hour
Cooling system	Pressurized water circulated by a
, , , , , , , , , , , , , , , , , , ,	centrifugal pump with thermostat
Lubrication system	Pressurized oil fed by a gear
	flow and by-pass cartridge filters.
	Electric, 24V-5kW
	Alternator, 24V-25A
	Mechanical
Air cleaner	Dry type filter



### HYDRAULIC SYSTEM

Two pumps are controlled by the Kato developed "APC" (Automatic Power Control) system, which senses where power is needed and automatically adjusts the pressure and flow-rate of the pump to match the work load. New "APC" system enables pump output to be utilized to the full with minimum fuel consumption. The adoption of joint circuit enables dual speed for boom derricking and arm extension/retraction.

rottaction.	
Pumps Double variable	piston pump and gear pump
Max. discharge flow	2×115 lit./min.
Commence of the control of the contr	2×30.4 US gal./min.
Max. discharge pressure	
	285kg/cm <sup>2</sup> (4,050 psi)
Max. discharge pressure (t	ravel circuit only)
_ (2)	335kg/cm <sup>2</sup> (4,760 psi)
	full-flow filter with replaceable e filter, a pilot line filter and a suction strainer
	section multiple control valve gic valves (with service port)
	Gear type
	inned tube, forced ventilation
	Primary and secondary
	on each circuit



### TRAVEL SYSTEM

Spring-applied idlers protect the drives from shock. Adjust cylinder is provided for easy arrangement of the track tensioning. An all welded undercarriage frame gives clog-free clearance, and the drive motors are neatly housed inside the track frame. The crawler tracks with interchangeable shoes are supported by 6 lower rollers and 1 upper roller on each side. Traveling motors ......Independent axial piston motor with reduction for each side Brakes ...... Independent disk parking brakes for each side, applied automatically when the travel levers are in the neutral position. Track shoes ......41 each side Track adjustment..... Grease cylinders with recoil springs Lubircation...... Sealed-for-life rollers and front idlers with floating seals Travel speed ...... High 0~5.5km/h (0~3.4mph) Low 0~3.7km/h (0~2.3mph) Gradeability ...... 70% (35°) Ground clearance (less grouser bar) ..... 440mm (1'05")



### **CAB & CONTROLS**

Standard cab accessories..... Front screen wiper,

water temperature, water level, fuel level,

battery charge and air cleaner



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### **SWING SYSTEM**

The hydraulic gear-driven swing is powered by an axial piston motor that is flange-connected to a planetary reduction unit. It rotates 360° continuously on the single row-ball bearing that has an integral, internally cut swing gear, and is totally enclosed to prevent the ingress of mud and water.



### BOOM, ARM AND BUCKET

The boom and arm are of all-welded, steel box section type with reinforced pin joints. Bucket is fabricated from



### REFILLING CAPACITY

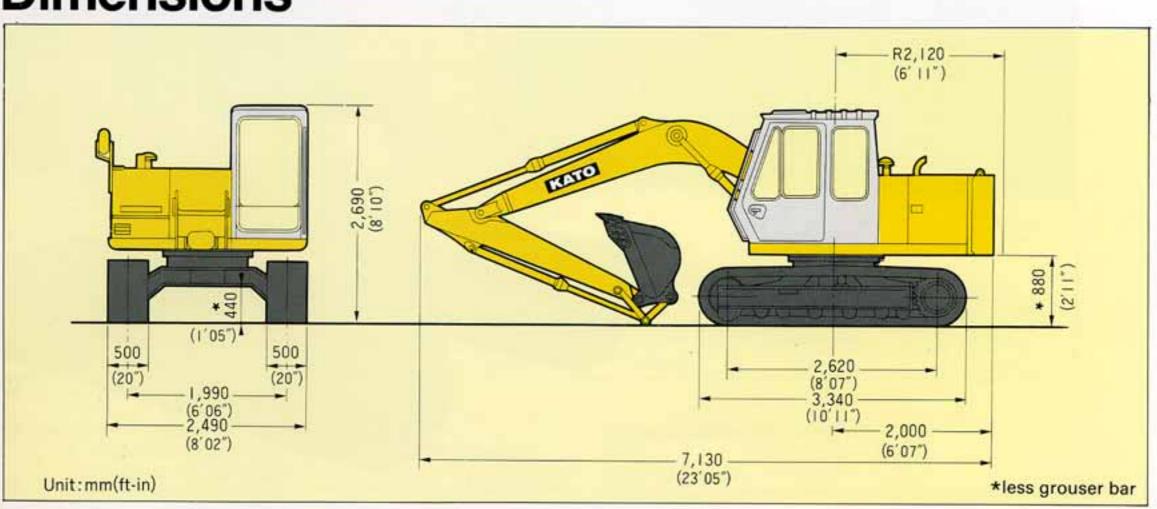
Fuel tank	250 lit. (66 US gal.)
Cooling system	
Engine oil	
Track drives	.2×3.2 lit. (2×0.8 US gal.)
Swing drive	
Hydraulic oil tank	*
(level)	80 lit. (21 US gal.)
(system)	



### WEIGHT

In standard figure, with the 2.25m (7'05") arm, 500mm (20") grouser shoes and 0.40m<sup>3</sup> CECE heaped (0.60 yd<sup>3</sup>. SAE heaped) bucket.

### **Dimensions**







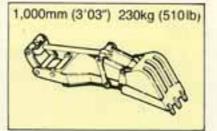
Unit: m (ft-in)

8
7
6
5
3
2
-0 B
2
3
4
-5
6
7 2.44m (8ft)
9 8 7 6 5 4 3 2 1 0 Meters 25 20 15 10 5 0 Feet

Arm Range	Short Arm 1.95 (6'05")	STD Arm 2.25 (7'05")	Long Arm 2.8 (9'02")
Max. digging radius	7.43 (24'04")	7.71 (25'04")	8.12 (26'07")
(B)— Max. digging reach at ground level	7.28 (23'11")	7.57 (24'01")	7.99 (26'02")
©∸ Max. digging depth	4.77 (15'07")	5.07 (16'08")	5.62 (18'05")
⊕ Max. digging height	7.91 (25'11")	8.08 (26'06")	8.08 (26'06")
⑥ Max. dumping height	5.55 (18'03")	5.72 (18'09")	5.78 (19'00')
⑥ Min. dumping height	2.28 (7'06")	1.97 (6'06")	1.44 (4'09")
⑥ Max. vertical wall	4.22 (13'10")	4.52 (14'10")	4.57 (15'00")
⊕− Min. swing radius	2.33 (7'08")	2.32 (7'07")	2.49 (8'02")
①*- Max. digging depth (8 ft level bottom)	4.52 (14'10")	4.85 (15'11")	5.41 (17'09")

### **Extension Arm**

\* Less grouser bar.



### **Bucket**

Type of buck	bucket Backhoe bucket							Dredging bucket	Slope form- ing bucket	Grab bucket	Ejector bucket	Rock bucket	Ripper
Bucket m <sup>3</sup> , CECE capacity m <sup>3</sup> (yd <sup>3</sup> ), PCSA (SAE)		0.22 0.25 (0.33)	0.30 0.34 (0.44)	0.35 0.40 (0.52)	0.40 0.46 (0.60)	0.45 0.51 (0.67)	0.50 0.57 (0.75)	0.40	2	0.30 (0.39) (struck)	0.30 0.33 (0.43)	0.25	=
Bucket	W/o side cutters mm (in)	500 (20°)	650 (26°)	740 (29°)	830 (33°)	860 (34")	940 (37")	2,000 (78.7°) 45° 300 (11.8°)	1,800 (70.9°)	750 (29.5°)	485 (19°)	680 (26.7°)	=
width	with side cutters mm (in)	590 (23")	740 (29°)	830 (33")	920 (36°)	950 (37°)	1,030 (41")		1,140 (39.4")	Ξ		790 (31.1°)	- 7
Bucket weig	ght kg Ib	270 595	330 728	350 772	370 816	400 882	420 926	420 930	470 1,040	550 1,210	375 830	615 1,360	215 470
Number of bucket teeth		3	4	4	4	5	5	2	12.5	4+4	3	5	- 1
Shapes of bucket						Q	See			Contraction of the Contraction o	9	(1)	8
	Short arm	•	•	•	•	•	- 0	•	0	•	•		
Standard boom	Standard arm	•	•	•	•	A	D	•	0	•	•		
	Long arm	•	•	<b>A</b>	A*	×	×	<b>A</b>	0	×	•	×	×
	Extension arm	•	×	×	×	×	×	×	×	×	•	- ×	×

● General purpose Light work Rock digging Loading Usable × Unusable Yellow colored are means standard.

'Shoe width should be 700mm (28').

### Track Shoes

			Grouser shoe	Flat shoe	Triangle shoe	
Types of shoes		9	and the state of t			
Shoe width	mm (in.)	500 (20")	600 (24")	700 (28")	500 (20")	700 (28")
Overall width	mm (ft. in.)	2,490 (8'02")	2,590 (8'06")	2,690 (8'10")	2,490 (8'02")	2,690 (8'10")
Ground pressure	kgf/cm² (psi)	0.36 (5.12)	0.31 (4.41)	0.27 (3.84)	0.38 (5.40)	0.28 (3.98)
Net weight change	kg (lb)	S.T.D.	+150 (330)	+300 (660)	+370 (820)	+660 (1460)

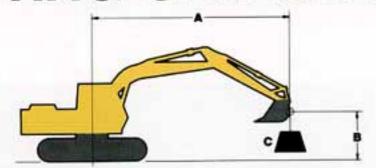
Yellow colored area means standard.

- Options: · APC system (APC, Auto-Slow)
  · Pre-cleaner and Double element for air cleaner
  · Electric refueling pump
  · 24V-40A Alternator

  - · Hydraulic piping for breaker

- · Hydraulic piping for spare port
- · Radio
- · Room fan
- · Room heater
- · Air-conditioner

### LIFTING CAPACITIES



A: REACH FROM SWING CENTERLINE

B: BUCKET HOOK HEIGHT

C: LIFTING CAPACITIES

U : OVER FRONT:

☼ : OVER SIDE OR 360°

HD-400VII 4.30m Boom 1.95m Arm

Equipped with 500mm Shoes and 0.40m3 (CECE heaped) Bucket

Unit: 1000kg

LOAD					LOAD	RADIUS		A	r	m		MAXIMUM		
POINT	2	2.00 3.00			4.00		5.00		6.00		LOAD RADIUS			
HEIGHT B m	Ö	<b>⊕</b>	å	(D)=	å	(D)=	ů	(C)=	å	0.	ů	000	m	
7.00											*1.13	*1.13	4.40	
6.00											*0.97	*0.97	5.57	
5.00							*2.26	2.18			*0.89	*0.89	6.30	
4.00					*2.35	*2.35	*2.30	2.17		11	*0.86	*0.86	6.78	
3.00			*3.65	*3.65	*2.90	*2.90	*2.56	2.10	1.96	1.52	*0.86	*0.86	7.05	
2.00					*3.61	2.87	2.60	2.01	1.92	1.48	*0.88	*0.88	7.16	
1.00					3.59	2.72	2.51	1.93	1.87	1.43	*0.93	*0.93	7.09	
0.00					3.50	2.63	2.45	1.87	1.83	1.40	*1.01	*1.01	6.86	
-1.00			*5.52	4.17	3.46	2.60	2.42	1.84	1.82	1.39	*1.14	*1.14	6.4	
-2.00	*4.36	*4.36	5.81	4.21	3.48	2.61	2.43	1.85			*1.37	*1.37	5.78	
-3.00	*6.26	*6.26	*5.05	4.29	3.54	2.67					*1.81	*1.81	4.7	

HD-400VII 4.30m Boom 2.25m Arm

Equipped with 500mm Shoes and 0.40m3 (CECE heaped) Bucket

Unit: 1000kg

quippeu	d with Southin Shoes and 0.40m				(OLOL	neapeu)		OTHE. TOOOK					
LOAD					The second second second	LOAD RADIUS A				n	MAXIMUM		
POINT	2	.00	3.	00	4.	4.00 5.00		6.	00	LOAD RADIUS			
HEIGHT B m	ð	0-	ð	(D)-	ů	<b>⊕</b>	ů	(C)=	å	(D)0	ů	(D)=0	m
7.00											*0.94	*0.94	4.88
6.00											*0.81	*0.81	5.94
5.00							*2.03	*2.03			*0.75	*0.75	6.62
4.00							*2.12	*2.12	*1.87	1.57	*0.73	*0.73	7.07
3.00			*3.19	*3.19	*2.66	*2.66	*2.40	2.13	1.98	1.54	*0.73	*0.73	7.34
2.00			*4.78	4.62	*3.39	2.92	2.63	2.04	1.94	1.50	*0.75	*0.75	7.43
1.00					3.64	2.76	2.54	1.95	1.88	1.45	*0.79	*0.79	7.38
0.00			*4.83	4.18	3.52	2.65	2.46	1.88	1.84	1.41	*0.87	*0.87	7.16
-1.00	*2.97	*2.97	5.76	4.16	3.47	2.61	2.42	1.84	1.82	1.39	*0.98	*0.98	6.75
-2.00	*3.96	*3.96	5.79	4.19	3.47	2.60	2.42	1.84	1.83	1.40	*1.17	*1.17	6.13
-3.00	*6.60	*6.60	*5.40	4.26	3.51	2.64	2.46	1.88			*1.54	*1.54	5.19
-4.00			*4.12	*4.12	*3.02	2.75							

HD-400VII 4.30m Boom 2.80m Arm

Equipped with 500mm Shoes and 0.40m3 (CECE heaped) Bucket

Unit:	1000kg
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quipped	with 50	umm Si	ioes and	0.40111	(CECE	neapeu/	Ducket					Offic	TOOOK
LOAD POINT HEIGHT B m					LOAD RADIUS		A		m		MAXIMUM		
	2.00 3		00	4.	00	5.00		6.00		LOAD RADIUS			
	å	(D)0	ů	<u>ې</u>	ů	(C)o	ů	0	ů	0=	ů	(C)>0	m
7.00		DV.									*0.98	*0.98	5.54
6.00		1					*1.71	*1.71			*0.89	*0.89	6.46
5.00	7								*1.45	*1.45	*0.85	*0.85	7.09
4.00							*1.76	*1.76	*1.85	1.60	*0.84	*0.84	7.51
3.00	-						*2.06	*2.06	*2.00	1.56	*0.85	*0.85	7.76
2.00			*3.83	*3.83	*2.90	*2.90	*2.47	2.07	1.95	1.51	*0.88	*0.88	7.85
1.00			*5.30	4.42	*3.66	2.80	2.56	1.97	1.89	1.45	*0.95	0.90	7.79
0.00			5.80	4.19	3.53	2.66	2.46	1.88	1.83	1.40	*1.04	0.93	7.58
-1.00	*3.41	*3.41	5.71	4.11	3.45	2.58	2.40	1.82	1.79	1.36	*1.19	1.01	7.21
-2.00	*5.30	*5.30	5.70	4.10	3.42	2.55	2.38	1.80	1.78	1.35	*1.42	1.17	6.64
-3.00	*6.94	*6.94	5.75	4.15	3.44	2.57	2.39	1.81	2		*1.84	1.49	5.80
-4.00	*6.75	*6.75	*4.93	4.25	3.51	2.64							

### NOTE:

- 1) Lifting capacities are based on SAE J1097.
- 2) Lifting capacities shown do not exceed 87% of machine hydraulic capacity or 75% of minimum tipping load.
- Capacities marked with an asterisk(\*) are limited by hydraulic capacities.
- Lifting capacities are based on machine standing on firm, uniform supporting surface.
   User must make allowances for job conditions such as soft or uneven ground.
- 5) Lifting capacities shown should not be exceeded. Weight of all lifting accessories must be deducted from the above lifting capacities.
- 6) Capacities apply only to the machine as originally manufactured and equipped by KATO WORKS CO., LTD.



HD-400VII 4.30m (14'1") Boom 1.95m (6'5") Arm

Equipped with 500mm (20") Shoes and 0.46m3 (0.60yd3) (PCSA heaped) Bucket

Unit: 1000lb (1000kg)

LOAD POINT HEIGHT B ft. in.	LOAD RADIUS A ft. in. (m)								MAXIMUM			
	5'0" (1.52)		10'0" (3.05)		15'0"	15'0" (4.57)		20'0" (6.10)		LOAD RADIUS		
	ů	<b>⊕</b>	ð	© ∞	ů	(C)o	ů	\$	ð	(D)=	ft. in. (m)	
20'0" (6.10)									*2.15 (0.98)	*2.15 (0.98)	18'0" (5.48)	
15'0" (4.57)					*4.85 (2.20)	*4.85 (2.20)			*1.92 (0.87)	*1.92 (0.87)	21'5" (6.53)	
10'0" (3.05)			*7.77 (3.52)	*7.77 (3.52)	*5.86 (2.66)	5.39 (2.45)	4.20 (1.90)	3.25 (1.48)	*1.89 (0.86)	*1.89 (0.86)	23'1" (7.05)	
5′0″ (1.52)					6.52 (2.96)	5.00 (2.27)	4.06 (1.84)	3.13 (1.42)	*1.98 (0.90)	*1.98 (0.90)	23′5″. (7.15)	
0'0" (0.00)					6.22 (2.82)	4.73 (2.14)	3.94 (1.79)	3.01 (1.37)	*2.22 (1.01)	*2.22 (1.01)	22'6" (6.86)	
-5'0" (-1.52)			12.37 (5.61)	8.97 (4.07)	6.14 (2.79)	4.65 (2.11)			*2.74 (1.24)	*2.74 (1.24)	20'1" (6.13)	
-10'0" (-3.05)			*10.89 (4.94)	9.21 (4.18)	6.29 (2.86)	4.80 (2.17)					12.	

HD-400VII 4.30m (14'1") Boom 2.25m (7'5") Arm

Unit: 1000lb

Equipped with 500mm (20") Shoes and 0.46m3 (0.60yd3) (PCSA heaped) Bucket (1000kg) LOAD RADIUS ft. in. (m) LOAD POINT HEIGHT B ft. in. (m) MAXIMUM LOAD RADIUS 10'0" 15'0" 20'0" 5'0" (1.52)(3.05)(4.57)(6.10)ů d 0 8 ů ft. in. (m) 0 0 0 0 0 19'2" (5.85) \*1.81 (0.82) \*1.81 (0.82) 20'0" (6.10) \*1.63 (0.74) 15'0" (4.57) \*4.39 (1.99) \*4.39 (1.99) \*1.63 (0.74) 22'5" (6.84) \*5.45 (2.47) \*1.60 (0.73) 24'0" (7.33) 10'0" (3.05) \*6.80 (3.08) \*6.80 (3.08) \*5.45 (2.47) 4.25 (1.93) 3.31 (1.50) \*1.60 (0.73) 4.10 (1.86) 3.16 (1.43) \*1.69 (0.77) 6.60 (2.99) 5.08 (2.30) \*1.69 (0.77) 24'4" (7.42) 5'0" (1.52) 3.96 (1.80) 23'6" (7.16) \*11.45 (5.19) 8.97 (4.07) 6.26 (2.84) 4.77 (2.16) 3.03 (1.37) \*1.91 (0.87) \*1.91 (0.87) (0.00) 8.94 (4.06) 6.14 (2.79) 4.65 (2.11) 3.92 (1.78) 2.98 (1.35) \*2.36 (1.07) \*2.36 (1.07) 21'2" (6.46) -5'0" (-1.52) \*7.62 (3.46) 12.34 (5.60) \*7.62 (3.46) 6.23 (2.83) 4.74 (2.15) \*11.65 (5.28) 9.14 (4.14) \*3.45 (1.56) \*3.45 (1.56) 16'10" (5.13) -10'0" -3.05)

HD-400VII 4.30m (14'1") Boom 2.80m (9'2") Arm

Unit: 1000lb

LOAD				LOAD RADIUS			A	ft. in. (m)	MAXIMUM		
LOAD POINT HEIGHT B ft. in. (m)	5'0"	(1.52)	10'0"	(3.05)	15'0"	(4.57)	20'0"	(6.10)	LOAD RADIUS		
	ů	©-	ő	•©	å	<b>©</b>	ů	<b>⊕</b>	ů	, C	ft. in. (m)
20′0″ (6.10)									*1.98 (0.90)	*1.98 (0.90)	21'0" (6.39)
15′0″ (4.57)							*3.67 (1.67)	3.44 (1.56)	*1.85 (0.84)	*1.85 (0.84)	23'11" (7.29)
10'0" (3.05)					*4.58 (2.08)	*4.58 (2.08)	4.31 (1.95)	3.35 (1.52)	*1.87 (0.85)	*1.87 (0.85)	25'5" (7.75)
5′0″ (1.52)			*9.91 (4.49)	*9.91 (4.49)	*6.37 (2.89)	5.16 (2.34)	4.12 (1.87)	3.17 (1.44)	*2.00 (0.91)	1.99 (0.90)	25'9" (7.84)
0′0″ (0.00)			12.42 (5.63)	9.00 (4.08)	6.27 (2.85)	4.77 (2.16)	3.93 (1.78)	3.00 (1.36)	*2.29 (1.04)	2.06 (0.93)	24'11" (7.58)
-5'0" (-1.52)	*7.73 (3.51)	*7.73 (3.51)	12.18 (5.53)	8.79 (3.99)	6.07 (2.75)	4.58 (2.08)	3.83 (1.74)	2.90 (1.32)	*2.85 (1.29)	2.39 (1.08)	22'9" (6.94)
-10'0" (-3.05)	*13.11 (5.95)	*13.11 (5.95)	12.31 (5.58)	8.90 (4.04)	6.08 (2.76)	4.59 (2.08)			*4.12 (1.87)	3.33 (1.51)	18'10' (5.75)
-15'0" (-4.57)			*8.83 (4.01)	*8.83 (4.01)	W N					Non-it	Visitado

#### NOTE:

- Lifting capacities are based on SAE J1097.
- 2) Lifting capacities shown do not exceed 87% of machine hydraulic capacity or 75% of minimum tipping load.
- Capacities marked with an asterisk(\*) are limited by hydraulic capacities.
- Lifting capacities are based on machine standing on firm, uniform supporting surface. User must make allowances for job conditions such as soft or uneven ground.
- 5) Lifting capacities shown should not be exceeded. Weight of all lifting accessories must be deducted from the above lifting capacities.
- 6) Capacities apply only to the machine as originally manufactured and equipped by KATO WORKS CO., LTD.

Address inquiries to:

NOTE: Westertions may include entired equipment KATO products and executions are subject to improvements and changes without notice.

NOTE: Illustrations may include optional equipment. KATO products and specifications are subject to improvements and changes without notice.



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